
Scheduling Algorithms for Multiprogramming in a Hard Real-time Environment

C. Liu and J. Layland

Journal of the ACM, 20(1):46--61, January 1973.

Real-Time Computing and Communications Lab., Hanyang University
<http://rtcc.hanyang.ac.kr>

Contents

- 1. Introduction and Background**
- 2. The Environment**
- 3. A Fixed Priority Scheduling Algorithm**
- 4. Achievable Processor Utilization**
- 5. The Deadline Driven Scheduling Algorithm**

Real-Time Computing and Communications Lab., Hanyang University
<http://rtcc.hanyang.ac.kr>

Introduction and Background

- ❑ The use of computers for
 - Time-critical control and monitoring of industrial processes
- ❑ Two scheduling algorithms are studied
 - Both are **priority driven and preemptive**
 - The processing of any task is interrupted by a request for any higher priority task
 - The first one
 - Fixed priority assignment algorithm
 - The second one
 - Dynamic priority assignment

The Environment

- ❑ Five assumptions
 - (A1) The request for all tasks for which **hard deadlines** exist are **periodic**
 - (A2) Deadlines consist of **run-ability constraints** only
 - Each task must be completed before the next request for it occurs
 - (A3) The tasks are **independent** in that requests for a certain task do not depend on the initiation or the completion of requests for other tasks
 - (A4) **Run-time for each task is constant** for that task and does not vary with time. Run-time here refers to the time which is taken by a processor to execute the task without interruption
 - (A5) Any nonperiodic tasks in the system are special; they are initialization or fault-recovery routines; they displace periodic tasks while themselves are being run, and do not themselves have hard, critical deadlines

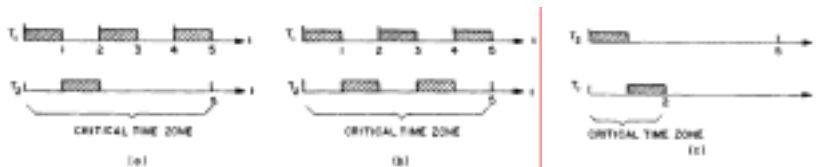
A Fixed Priority Scheduling Algorithm (3)

□ Important value of Theorem 1

- A simple direct calculation can determine whether or not a given priority assignment will yield a feasible scheduling algorithm

□ Example: two tasks τ_1 and τ_2

- $T_1 = 2, C_1 = 1$
- $T_2 = 5, C_2 = 1$



A Fixed Priority Scheduling Algorithm (4)

□ The following inequalities must be met for feasibility

- If τ_1 is the highest priority task (method 1)
 - $\lfloor T_2/T_1 \rfloor C_1 + C_2 \leq T_2$. (1)
- If τ_2 is the highest priority task (method 2)
 - $C_1 + C_2 \leq T_1$. (2)
- It follows from (2) that
 - $\lfloor T_2/T_1 \rfloor C_1 + \lfloor T_2/T_1 \rfloor C_2 \leq \lfloor T_2/T_1 \rfloor T_1 \leq T_2$

□ Whenever $T_1 \leq T_2$ and τ_2 has the highest priority, Ineq.(2) implies Ineq.(1)

- Ineq.(1) is a weaker condition
- If a task set is schedulable by method 2, then it is also schedulable by method 1

A Fixed Priority Scheduling Algorithm (5)

- ❑ Reasonable rule of priority assignment
 - Assign priorities according to request rates, independent of run-times
 - Tasks with higher request rates will have higher priorities
- ❑ Rate-monotonic priority assignment
 - Optimum in the sense that no other fixed priority assignment rule can schedule a task set which cannot be scheduled by the rate-monotonic priority assignment
- ❑ Theorem 2. If a feasible priority assignment exists for some task set, the rate monotonic priority assignment is feasible for that task set
 - Proof. By an inter-change argument

Achievable Processor Utilization (1)

- ❑ Utilization factor
 - The fraction of processor time spent in the execution of the task set
 - The utilization factor is equal to one minus the fraction of idle processor time
 - $$U = \sum_{i=1}^n (C_i/T_i).$$
 - Utilization factor can be improved by
 - Increasing run-times and decreasing periods
 - However, utilization factor is upper bounded by the requirement of feasibility (meeting deadlines)
 - How large the processor utilization factor can be?

Achievable Processor Utilization (2)

□ Full utilization of processor

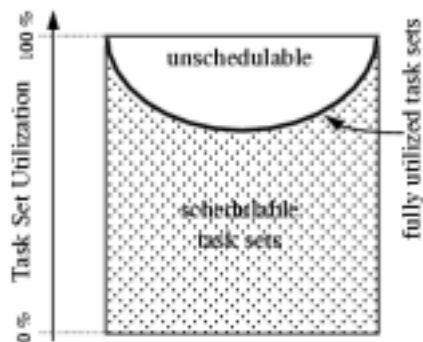
- A set of tasks is said to “fully utilize” the processor if the priority assignment is feasible for the set and if an increase in the run-time of any of the tasks in the set will make the priority assignment infeasible

□ LUB (least upper bound) of utilization factor

- The minimum of utilization factor over all sets of tasks that fully utilize the processor
- For all task sets whose utilization factor is below this bound, there exists a fixed priority assignment which is feasible

Achievable Processor Utilization (3)

□ Schedulable Utilization Bound



Achievable Processor Utilization (4)

□ Theorem 3. For a set of two tasks with fixed priority assignment, the least upper bound to the processor utilization factor is $U = 2(2^{1/2} - 1)$

□ Proof. See Theorem 4

Achievable Processor Utilization (5)

□ Theorem 4. For a set of m tasks with fixed priority order, and the restriction that the ratio between any two request periods is less than 2, the least upper bound to the processor utilization factor is $U = m(2^{1/m} - 1)$

□ Proof.

- (1) We first show that the LUB can be found when
 - $C_1 = T_2 - T_1$, $C_k = T_{k+1} - T_k$, and
 - $C_m = T_m - 2(C_1 + C_2 + \dots + C_{m-1}) = 2T_1 - T_m$
- (2) We then compute the LUB

Achievable Processor Utilization (6)

□ We first show that the LUB can be found when

▪ $C_1 = T_2 - T_1$, $C_k = T_{k+1} - T_k$, and $C_m = 2T_1 - T_m$

□ Proof (1). For $\Delta \geq 0$

▪ (1) Suppose that $C_1 = T_2 - T_1 + \Delta$ and the task set S fully utilize

- We can construct another set S' such that
- $C'_1 = T_2 - T_1$, $C'_2 = C_2 + \Delta$, and $C'_k = C_k$
- S' fully utilize since $C_1 + C_2 = C'_1 + C'_2$
- $U - U' = \Delta/T_1 - \Delta/T_2 \geq 0$

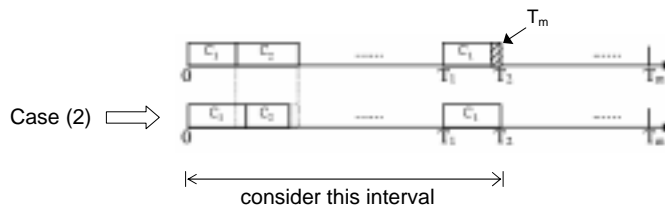
▪ (2) Suppose that $C_1 = T_2 - T_1 - \Delta$ and the task set S fully utilize

- We can construct another set S' such that
- $C'_1 = T_2 - T_1$, $C'_2 = C_2 - 2\Delta$, and $C'_k = C_k$
- S' fully utilize
- $U - U' = -\Delta/T_1 + 2\Delta/T_2 \geq 0$

▪ Similarly, we can show that $C_k = T_{k+1} - T_k$

Achievable Processor Utilization (7)

□ Illustration



Achievable Processor Utilization (8)

□ We next compute the LUB

□ Using the previous results, we can write

$$\begin{aligned} U &= (T_2 - T_1)/T_1 + (T_3 - T_2)/T_2 + \dots + (2T_1 - T_m)/T_m \\ &= T_2/T_1 - 1 + T_3/T_2 - 1 + \dots + 2T_1/T_m - 1 \\ &= T_2/T_1 + T_3/T_2 + \dots + 2T_1/T_m - m \end{aligned}$$

□ Let $R_i = T_{i+1}/T_i$

$$\frac{T_1}{T_m} = \frac{T_1}{T_m} \frac{T_{m-1} \dots T_3 T_2}{T_{m-1} \dots T_3 T_2} = \frac{T_{m-1} T_{m-2} \dots T_3 T_1}{T_m T_{m-1} \dots T_3 T_2} = 1 / R_{m-1} R_{m-2} \dots R_1$$

$$U = R_1 + R_2 + \dots + R_i + \dots + 2/(R_{m-1} \dots R_1) - m$$

Achievable Processor Utilization (9)

□ Given

$$U = R_1 + R_2 + \dots + R_i + \dots + 2/(R_{m-1} \dots R_1) - m$$

□ To find the minimum, we solve the following

$$\partial U / \partial R_i = 1 - 2(R_{m-1} \dots R_1) / (R_{m-1} \dots R_i \dots R_1)^2 = 0$$

$$R_i = 2 / (R_{m-1} R_{m-2} \dots R_2 R_1)$$

□ This implies $R_1 = R_2 = \dots = R_{m-1}$, thus $R_i = 2^{1/m}$

□ Finally it follows that

$$\begin{aligned} U &= (m-1)2^{\frac{1}{m}} + 2/(2^{\frac{m-1}{m}}) - m = (m-1)2^{\frac{1}{m}} + 2/(2^{1-\frac{1}{m}}) - m \\ &= (m-1)2^{\frac{1}{m}} + 2^{\frac{1}{m}} - m = m(2^{\frac{1}{m}} - 1) \end{aligned}$$

Achievable Processor Utilization (10)

- For $m=3$, $U = 3(2^{1/3} - 1) \approx 0.78$
- For large m , $U \approx \ln 2$
- The restriction that the largest ratio between request period less than 2 can be removed
- Theorem 5. For a set of m tasks with fixed priority order, the least upper bound to processor utilization is $m(2^{1/m} - 1)$

Achievable Processor Utilization (11)

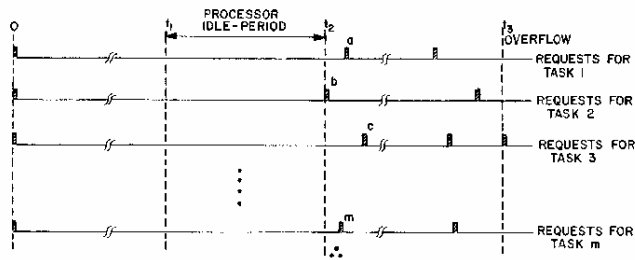
- Outline of proof of Theorem 5
 - The idea is that if a set of tasks fully utilizes the processor and for some i , $i < m$
 - $T_m/T_i \geq 2$,
 - then we can always construct another set of tasks that will
 - (1) fully utilize the processor,
 - (2) $T_m/T_i < 2$, and
 - (3) the utilization of the new set is less than the original one

The Deadline Driven Scheduling Algorithm (1)

- Priorities are assigned to tasks according to the deadlines of their current requests
 - A task will be assigned the highest priority if the deadline of its current request is the nearest
 - At any instant, the task with the highest priority and yet unfulfilled request will be executed
 - This method of assigning priorities is a dynamic one
- We want to establish a necessary and sufficient condition for the feasibility of the deadline driven scheduling algorithm

The Deadline Driven Scheduling Algorithm (2)

- Theorem 6. When the deadline driven scheduling algorithm is used to schedule a set of tasks on a processor, there is no processor idle time prior to an overflow
- Proof. Shifting a, b, ..., c to t_1 leads to a contradiction



The Deadline Driven Scheduling Algorithm (3)

- **Theorem 7.** For a given set of m tasks, the deadline driven scheduling algorithm is feasible if and only if

$$U = C_1/T_1 + C_2/T_2 + \dots C_m/T_m \leq 1$$

- **Proof.**

- (1) To show the necessity, compute the total demand of computation time

$$\begin{aligned} & (T_2 T_3 \cdots T_m) C_1 + (T_1 T_3 \cdots T_m) C_2 + \cdots + (T_1 T_2 \cdots T_{m-1}) C_m \\ & (T_2 T_3 \cdots T_m) C_1 + (T_1 T_3 \cdots T_m) C_2 \\ & \quad + \cdots + (T_1 T_2 \cdots T_{m-1}) C_m > T_1 T_2 \cdots T_m \\ & (C_1/T_1) + (C_2/T_2) + \cdots + (C_m/T_m) > 1 \end{aligned}$$

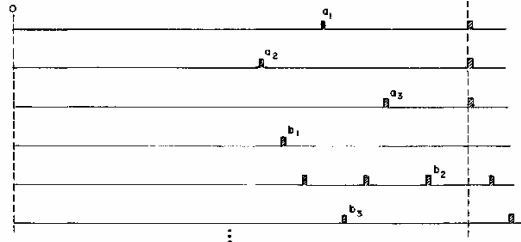
The Deadline Driven Scheduling Algorithm (4)

- **Proof of Theorem 7.**

- (2) To show the sufficiency, assume that the algorithm is not feasible and $U = C_1/T_1 + C_2/T_2 + \dots C_m/T_m \leq 1$
 - There will be an overflow at $t = T$ in the interval $[0, T_1 T_2 \dots T_m]$
 - There is no idle time in the interval $[0, T]$
 - Let $a_1, a_2, a_3, \dots, b_1, b_2, b_3, \dots$ denote the request times immediately before T
 - Let a_1, a_2, a_3, \dots are the request times of tasks with deadlines at T
 - Let b_1, b_2, b_3, \dots are the request times of tasks with deadlines beyond T

The Deadline Driven Scheduling Algorithm (5)

□ Proof of Theorem 7.



▪ Two cases must be considered

- Case 1. None of the computation times of requested at b_1, b_2, b_3, \dots was carried out before T
- Case 2. Some of the computation times of requested at b_1, b_2, b_3, \dots was carried out before T

The Deadline Driven Scheduling Algorithm (6)

□ Proof of Theorem 7.

▪ Case 1.

- The total demand of computation time in the interval $[0, T]$

$$\lfloor T/T_1 \rfloor C_1 + \lfloor T/T_2 \rfloor C_2 + \dots + \lfloor T/T_m \rfloor C_m$$

- Since there is no idle period

$$\lfloor T/T_1 \rfloor C_1 + \lfloor T/T_2 \rfloor C_2 + \dots + \lfloor T/T_m \rfloor C_m > T$$

- Thus

$$(T/T_1)C_1 + (T/T_2)C_2 + \dots + (T/T_m)C_m > T$$

$$(C_1/T_1) + (C_2/T_2) + \dots + (C_m/T_m) > 1$$

- This is a contradiction

The Deadline Driven Scheduling Algorithm (7)

□ Proof of Theorem 7.

▪ Case 2.

- There must exist a point T' such that none of requests at b_1, b_2, b_3, \dots was carried out in the interval $[T', T]$
- In other words, only those requests with deadline at or before T will be executed
- Note that since some of the requests at b_1, b_2, b_3, \dots can be executed until T' , all those requests initiated before T' with deadlines at or before T have been fulfilled before T'
- Therefore, the total demand of computation time in the interval $[T', T]$ is less than or equal to

$$\lfloor (T - T')/T_1 \rfloor C_1 + \lfloor (T - T')/T_2 \rfloor C_2 + \dots + \lfloor (T - T')/T_m \rfloor C_m$$

- Since an overflow occurs,

$$\lfloor (T - T')/T_1 \rfloor C_1 + \lfloor (T - T')/T_2 \rfloor C_2 + \dots + \lfloor (T - T')/T_m \rfloor C_m > T - T',$$

- $(C_1/T_1) + (C_2/T_2) + \dots + (C_m/T_m) > 1$, which is a contradiction